

# KNCTEK GPS Smart Antenna Module KSTO-1711 Specification

Version 2.0 2009/04/11

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## **KNCTEK Company LTD.**

14F-14, Byucksan Digital Valley 5<sup>th</sup>, 60-73, Gasangdong, Geumcheon-gu SEOUL, KOREA

> TEL: 82-2-839-5701 FAX: 82-2-830-5703

E-Mail: sales@knctek.com http://www.knctek.com





# **KSTO-1711 Specification**

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# **Revision History**

- 1. 2008-10-20 : Original Draft 1.0
- 2. 2008-12-15: Updated Version 1.0.1 for Mechanical Dimension
- 3. 2009-04-11 : Updated Version 2.0 for re-organized Electrical characteristics and performance characteristics chart on page 6&7.



# **KSTO-1711 Operational Manual**

## INTRODUCTION

The **KSTO-1711** is the newest generation of KNCTEK GPS Smart Antenna Receiver used Omni direction Antenna. The GPS Smart Antenna receiver is powered by STMicroelectronics technology and KNCTEK proprietary navigation algorithm that providing you more stable navigation data. The miniature design is the best choice to be embedded in a portable device like PND, PDA, Telematics and vehicle locator. The excellent sensitivity of **KSTO-1711** gets the great performance when going though the urban canyon and foliage environmental condition.

#### **PRODUCT FEATURES**

- ♦ 16 Channels High Performance GPS(HPGPS)
- ♦ 66MHz ARM7TDMI & Complete Embedded Memory System
  - Flash 256K bytes + 16K bytes and 64K bytes SRAM
- ♦ Operable from 3.3V/80mA Continuous Mode
- ♦ Galileo Ready GPS module in RF Front End
- ♦ Achieved -159dBm in Tracking Sensitivity
- ♦ Enhanced Warm/Hot Acquisition Sensitivity at -148dBm
- ♦ Fast TTFF <35seconds in Warm Start</p>
- ♦ Enhanced Algorithm for Navigation Stability
- Excellent Sensitive for Urban Canyon and Foliage Environmental condition
- ♦ Dual Multi-path Rejection
- ♦ Applied Static and Prediction Filters
- ♦ SBAS( WAAS and EGNOS) supported
- ♦ NMEA-0183 compliant protocol/custom protocol
- → Automotive-grade Quality GPS solution
- ♦ Small form factor (17.0mm X 53.0mm X 13.0pi)
- ♦ ODM/OEM development is fully supported Application Engineering
- ♦ Hardware and Software support from a dedicated GPS team



## PRODUCT APPLICATION

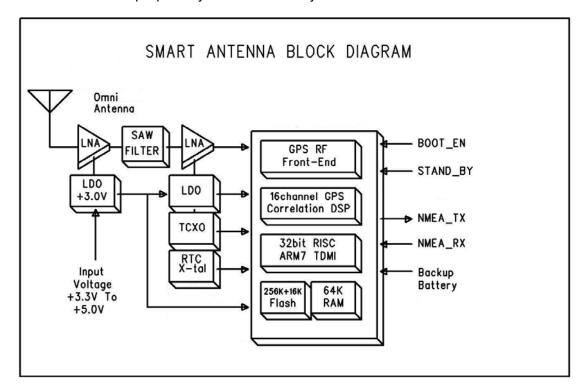
- Automotive applications
- ♦ Speed camera detector
- ♦ Personal and Car navigation
- ♦ Marine navigation
- ♦ Timing application

## PRODUCT PICTURE



## **KSTO-1711 SYSTEM BLOCK DIAGRAM**

The KSTO-1711 consists of STMicroelectronics MCM chipsets Technology, KNCTEK LNA and proprietary software. The system is described as follows.





## **TECHNICAL SPECIFICATION**

## 1. Electrical Characteristics

## 1.1 Absolute Maximum Rating

Parameter	Symbol	Min	Max	Units	
Power Supply					
Power Supply Volt.	VCC	-0.3	8	V	
Input Pins					
Input Pin Voltage I/O	RX	-0.3	3.6	V	
Backup Battery	Vbat	1.8	3.6	V	
Environment					
Operating Temperature	Topr	-40	85	°C	
Storage Temperature	Tstg	-40	125	°C	
Backup Battery operating temperature <sup>1</sup>	Tbat	-20	65	°C	
Peak Reflow Soldering Temperature < 10S	Tpeak		260	$^{\circ}$	
Humidity			95	%	

<sup>\*\* &</sup>lt;sup>1</sup> Backup Battery operating temperature depends on Battery characteristics

Note: Absolute maximum ratings are stress ratings only, and functional operation at the maximums is not guaranteed. Stress beyond the limits specified in this table may affect device reliability or cause permanent damage to the device.

For functional operating conditions, please refer to the operating conditions tables as follow.

## 1.2 Operating Condition

Parameter	Symbol	Condition	Min	Тур	Max	Units
Power supply voltage	Vcc		3.3	5.0	6.0	V
Power Supply voltage ripple	Vcc_PP	Vcc = 5.0V			30	mV
Acquisition current	IccA	Vcc = 3.3V		80	85	mA
Tracking current	IccT	Vcc = 3.3V		80	85	mA
Input high voltage	$V_{IH}$		2.0			V
Input low voltage	$V_{IL}$				0.8	V
Output high voltage	V <sub>OH</sub>		2.9			V
Output low voltage	V <sub>OL</sub>				0.4	V





## 2. General & Performance Specification

Parameter	Specification		
Receiver Type	L1 frequency band, 1575.42MHz, 16 Channels		
Sensitivity	Tracking	-159dBm	
	Re-acquisition	-151dBm	
	Acquisition( Warm Start) Sensitivity	-146dBm	
Accuracy	Position 2.0m CEP		
Acquisition Time	Cold Start 39 sec. typical (Open sky		
	Warm Start	34 sec. typical (Open sky)	
	Hot Start	2.5 sec. typical (Open sky)	
	Reacquisition Time	1 sec	
Power Consumption	Tracking & Acquisition	80mA @ 3.3V	
	Back-up	30uA @ 3V	
Navigation Data Update	1Hz		
Rate			
Operational Limits	Velocity	Max 515 m/s	
	Altitude	Max 18,000m	
	Acceleration	Less than 4g	
Mechanical data	Dimension	15.0X13.0X2.2mm	
	Weight	10grams ±5%	
Protocol	NMEA-0183 V3.0		

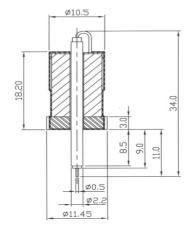
<sup>\*\* &</sup>lt;sup>1</sup>Open Sky means no obstructions in the sky



## **KSTO-1711 Specification**

## 3. Omni direction Antenna Specification



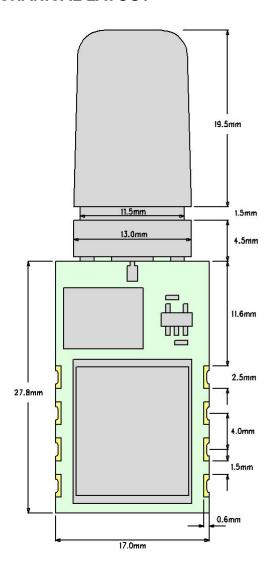


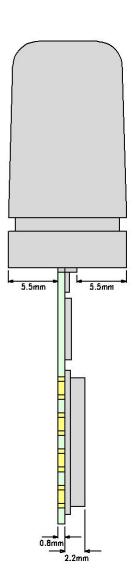
Parameter	Specification	
Dimension	Cylinder type, 10.5 pi x 18.2mm(without tube)	
Center Frequency	1575.43MHz	
Impedance	50 ohm	
Gain@Zenith	-5.0∼0 dBi typical	
Polarization	RHCP	
VSWR	1.5 : 1 Max	





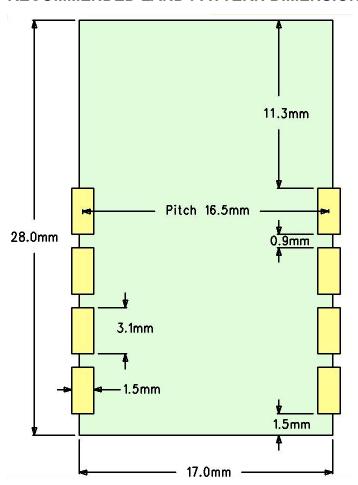
## **MECHANICAL LAYOUT**



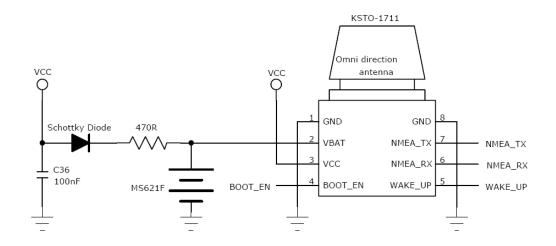




## RECOMMENDED LAND PATTERN DIMENSION



## **HARDWARE INTERFACE**





## **Pin Description**

PIN	SIGNAL NAME	I/O	DESCRIPTION	CHARACTER
1	GND	Р	Ground	Ground
2	VBAT	I	Backup Battery supply	DC +1.8V ~ +3.3V
3	VCC	Р	DC Power Supply Voltage input	DC +3.3V ±5%
4	BOOT_EN	I	BOOT MODE(Active HIGH)	
5	WAKE_UP	I	Enable Standby Mode	Active Low
6	NMEA_RX	I	UART RXA	NMEA_RXA
7	NMEA_TX	0	UART TXA	NMEA_TXA
8	GND	Р	Ground	Ground

#### **VCC**

This is the main power supply for the Engine board. The power range is DC +3.3V  $\pm$ 5%.

#### **GND**

GND provides the ground for the Engine board. Connect all grounds.

## NMEA\_TX

NMEA\_TX, UART output, 3.3V LVTTL logic level. This is the main transmit channel and is used to output navigation and measurement data to user written software. The default setup is NMEA Output, 9600bps, 8 data bits, no parity, 1 stop bit.

## NMEA\_RX

NMEA\_RX, UART input,3.3V LVTTL logic level. This is the main receiving channel and is used to receive software commands to the Engine board from user written software.

## **BOOT\_EN**

Pull BOOT\_EN pin high, then it will get into boot mode.





## **Packing Information**

TBD : To be determined



## **GPS Receiver User's Tip**

- GPS signal will be affected by weather and environment conditions, thus suggest to use the GPS receiver under less shielding environments to ensure GPS receiver has better receiving performance.
- 2. When GPS receiver is moving, it will prolong the time to fix the position, so suggest to wait for the satellite signals to be locked at a fixed point when first power-on the GPS receiver to ensure to lock the GPS signal at the shortest time.
- 3. The following situation will affect the GPS receiving performance:
  - a. Solar control filmed windows.
  - b. Metal shielded, such as umbrella, or in vehicle.
  - c. Among high buildings.
  - d. Under bridges or tunnels.
  - e. Under high voltage cables or near by radio wave sources, such as mobile phone base stations.
  - f. Bad or heavy cloudy weather.
- 4. If the satellite signals can not be locked or encounter receiving problem (while in the urban area), the following steps are suggested:
  - a. Please plug the external active antenna into GPS receiver and put the antenna on outdoor or the roof of the vehicle for better receiving performance.
  - b. Move to another open space or reposition GPS receiver toward the direction with fewer blockages.
  - c. Move the GPS receiver away from the interference resources.
  - d. Wait until the weather condition is improved.

While a GPS with a backup battery, the GPS receiver can fix a position immediately at next power-on if the build-in backup battery is full-recharged.





## **Contact Information Section**

Contact: <a href="mailto:sales@knctek.com">sales@knctek.com</a>

Web Site: www.knctek.com

Headquarter:

14F-14, 60-73 Byucksan Digital Valley 5<sup>th</sup>, Gasang-dong, Geumcheon-gu SEOUL, KOREA TEL: 82-2-839-5701

FAX: 82-2-830-5703

\* As for the explantion of NMEA-0183 V3.0 Protocol : Please refer to KNCTEK Website (www.knctek.com)